



# *Advanced IMPRINT Workshop*



Approved for public release  
Distribution unlimited



## *IMPRINT Team*

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# *Workshop Objectives*

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## **You will be able to...**

- ◆ Develop an advanced analysis using Advanced or Goal-oriented options
- ◆ Interpret results to complete analysis
- ◆ Demonstrate Advanced Workload techniques
- ◆ Demonstrate Goal Matrix programming
- ◆ Identify opportunities for use of IMPRINT capabilities

# Development of Analysis

OR

D . O . A



# Why Modeling?

Many Variables



Concept System

Too Dangerous

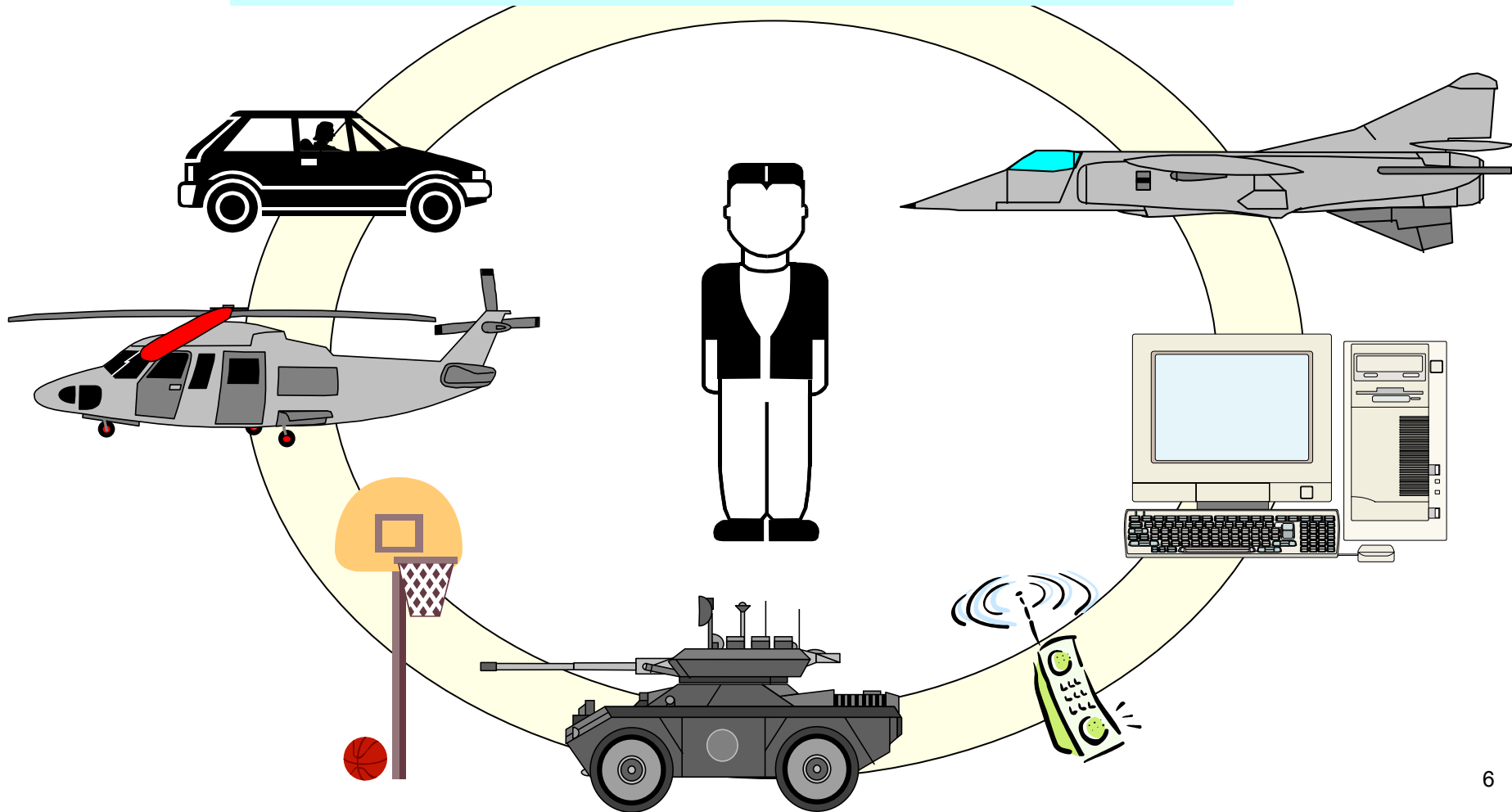


Field Study Not Feasible

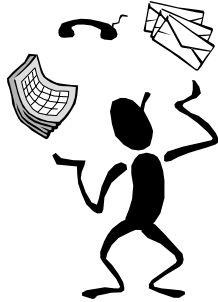
**Model – Test – Model**

# Why Human Performance Modeling?

System Performance =  $f(\text{human performance})$

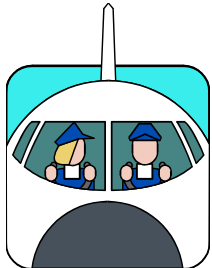
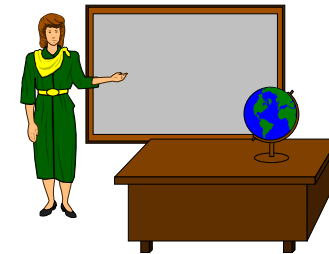


# *What Does Human Performance Modeling Tell Us?*



Is the human overloaded with tasks?

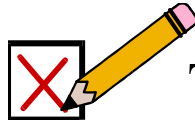
Will training improve human and system performance?



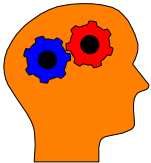
How to allocate tasks between human(s) and automation?

What are the performance tradeoffs with different system designs or levels of operator experience?

# Typical Measures



Task time and accuracy



Operator workload level



Number of operators  
required

Impact on  
System  
Performance

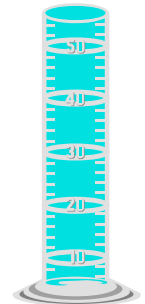


# Challenges to Human Performance Modeling

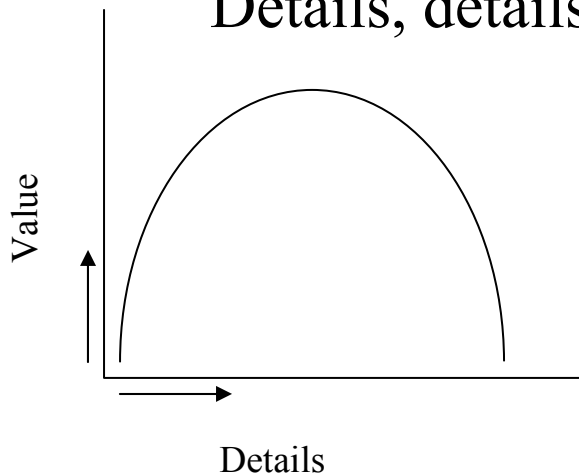
Clear questions



Appropriate measures



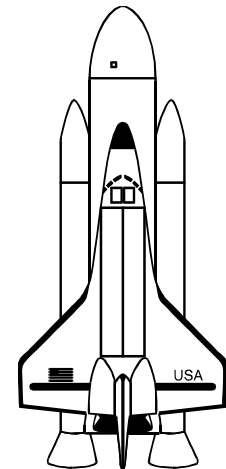
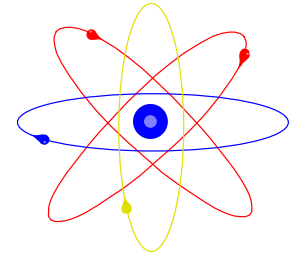
Details, details, details



Input data collection

# Scientific Method

- ◆ Determine the problem - What is your question? Observation!
- ◆ Make a hypothesis - What is your prediction?
- ◆ Test your hypothesis - What steps and measures are necessary? What tool?
- ◆ Analyze your results
- ◆ Draw conclusions



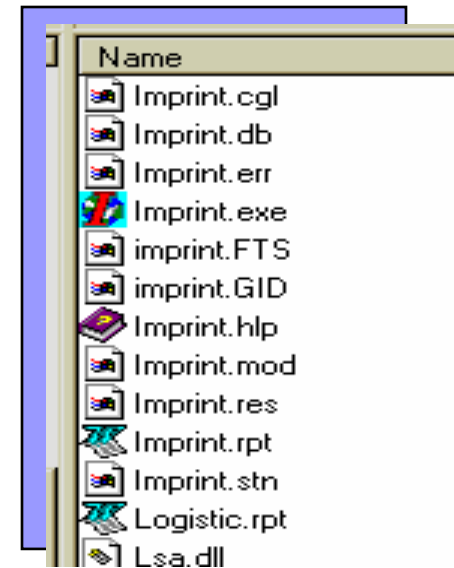
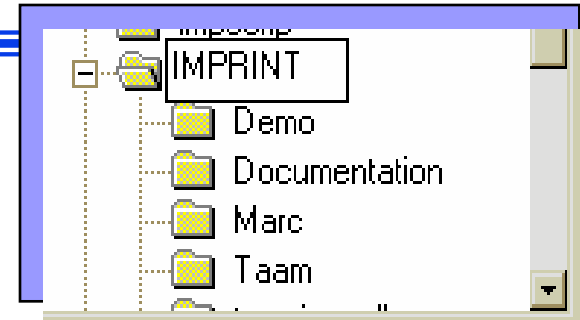


# *MERINT Review*

# The IMPRINT Directory

## ◆ What's in it

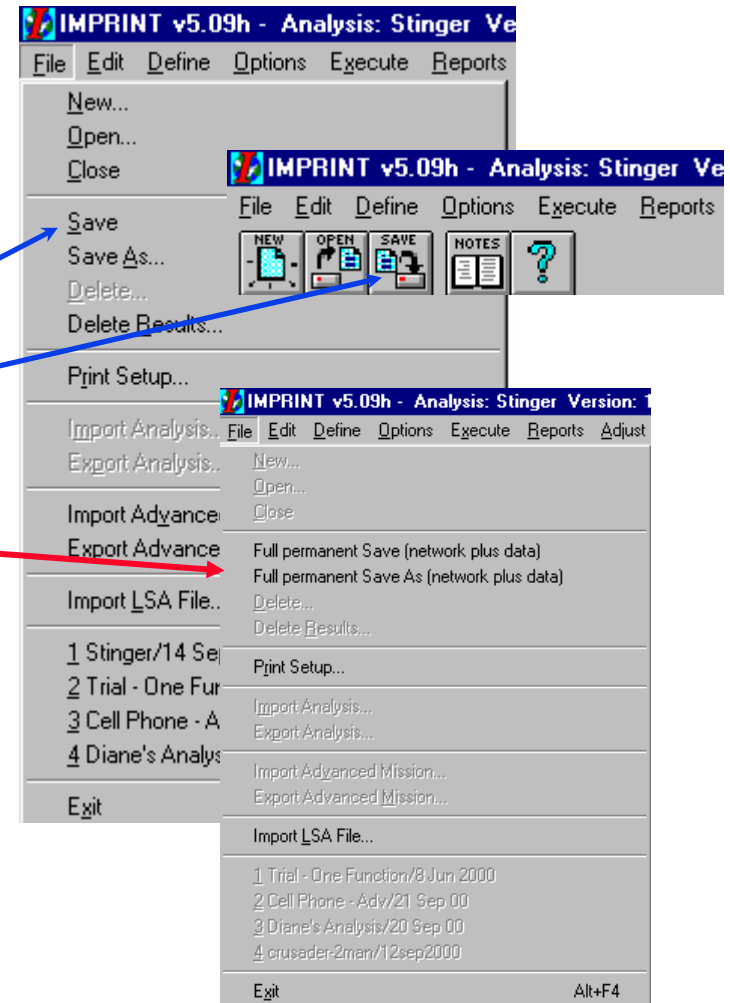
- Executable files, & DLL files
- IMPRINT database files
  - » “library” files - stuff that “comes with” IMPRINT
  - » “user” files - your stuff
  - » “working” or “session” files -  
for the open analysis
- Report files - linked to an analysis
- Help files
- Documentation & Readme
  - » Analysis Guide & User's Guide



## ◆ What isn't: Your analysis by name!

# Saving Your Analysis

- ◆ Save early, save often\*  
\*from the top-most window
- ◆ Save again as you exit
- ◆ Saving your analysis
- ◆ Saving your network diagram & information
- ◆ When in doubt, save
- ◆ Reminders are legitimate!

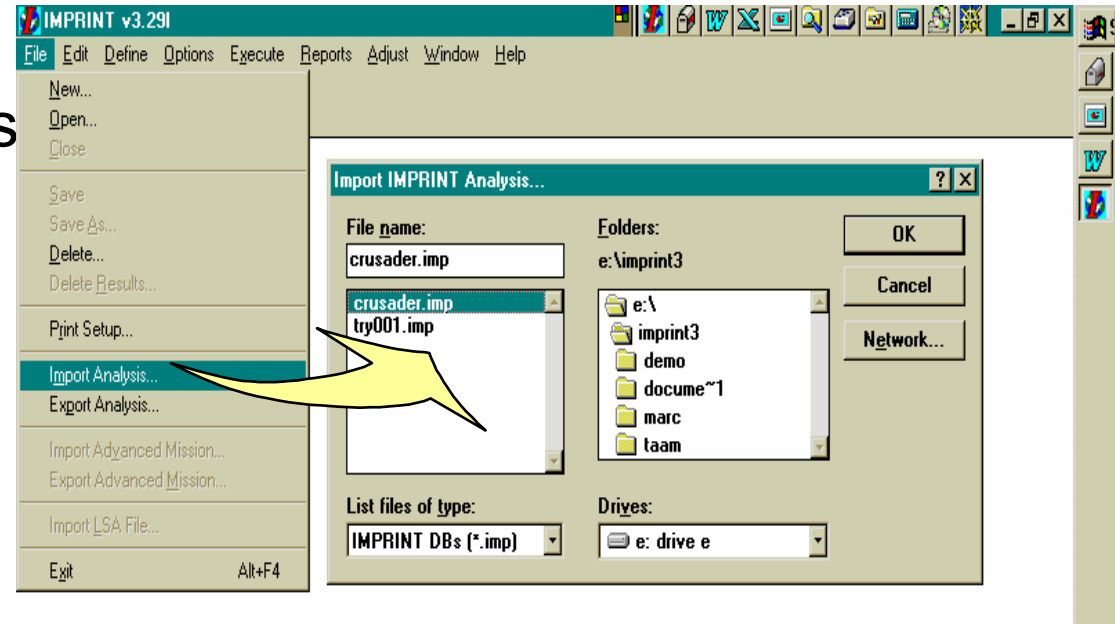




# Sharing Your Analysis Using Import & Export

## ◆ To Import -

- Close the open analysis
- Select “Import”
- Browse until you find the one you’re looking for
- To access the analysis, you must then open it



## ◆ To Export -

- Close your analysis if you have one open
- Select Export option
- Create export file using Windows naming conventions
- On hard drive or on disk
- File name does not have to = analysis name

***In IMPRINT, it's an analysis. Out of IMPRINT, it's a .imp file.***



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# *Introduction to Advanced Modeling*



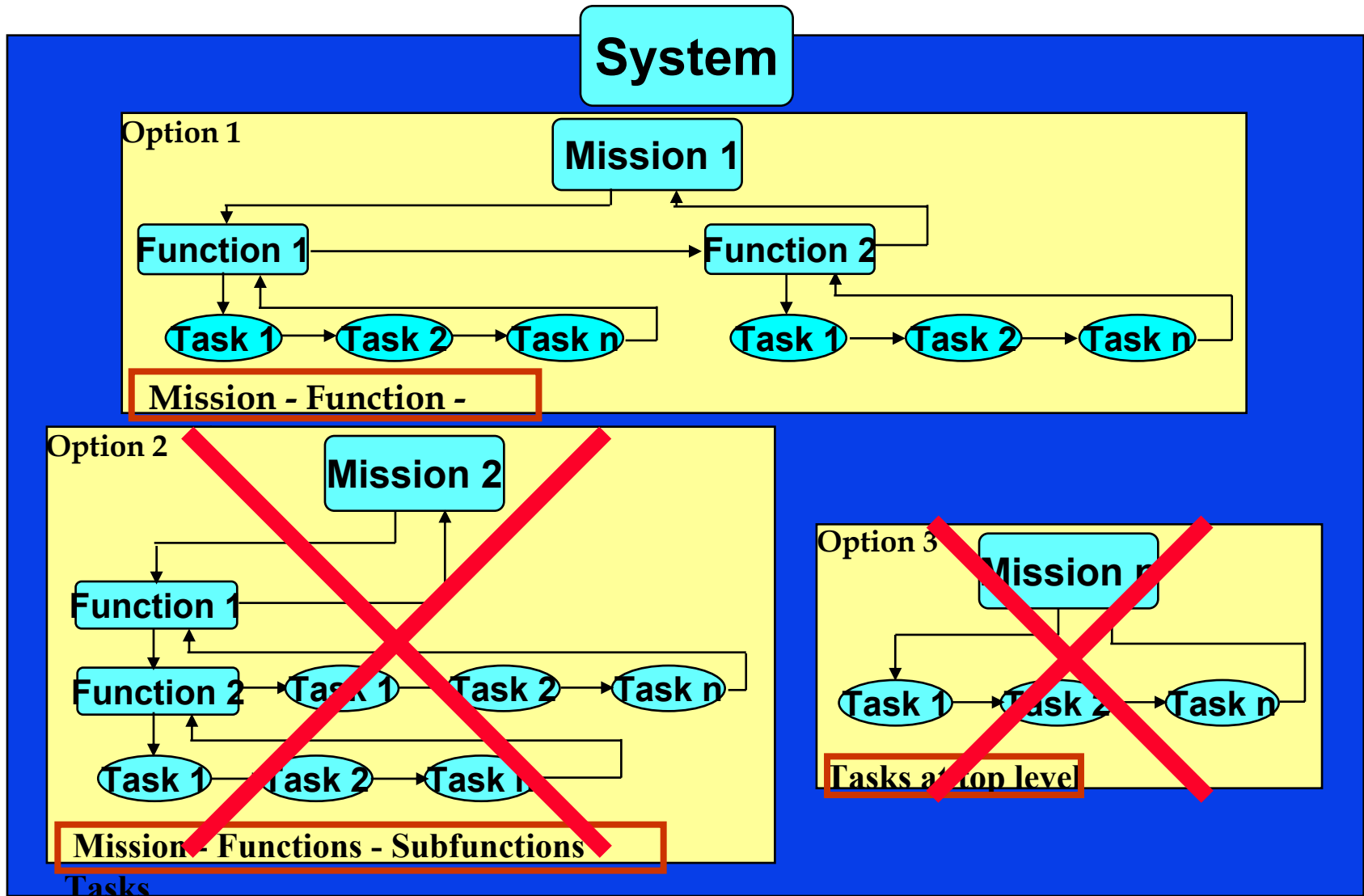
# *Advanced Modeling vs. Advanced workload*

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- ◆ Advanced modeling capabilities allow you greater flexibility in controlling the sequence of events in your model
  - Effects tab
- ◆ Advanced workload is another model for predicting workload based on multiple resource theory



# Task Network Hierarchy Options in Advanced





# Multiple Resources Theory of Mental Workload

**Mission Tasks**



**Which Brain Resources Involved?**



**Degree of Resource Use?**

1. monitor alarms

2. decide response action

3. pull trigger

•  
•  
•  
n. task n

**Visual**

**Cognitive**

**Auditory**

**Motor**

**Speech**



**Speech**

**Visual**

**Auditory**

**Motor**

**Cognitive**

- 0.0 No Cognitive Activity
- 1.0 Automatic (simple association)
- 1.2 Alternative Selection
- 3.7 Sign/Signal Recognition
- 4.6 Evaluation/Judgment (consider single aspect)
- 5.3 Encoding/Decoding, Recall
- 6.8 Evaluation/Judgment (consider several aspects)
- 7.0 Estimation, Calculation, Conversion

# *Unique Outputs of Advanced Workload*

- ◆ Critical Path
- ◆ Operator Activity
- ◆ Operator Workload
- ◆ Overload
- ◆ Channel Conflict
- ◆ Task Timeline
- ◆ CrewStation Workload
- ◆ User Snapshot



# *Branching Logic and Expressions*



# *Advanced Modeling Details*

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- ◆ Variables
- ◆ Mathematical and Logical Expressions
- ◆ Beginning Effects
- ◆ Ending Effects
- ◆ Release Conditions
- ◆ Data Collection

- ◆ Most variables are defined by the user to represent conditions or parameters
  - Examples
    - » Resource availability
    - » Entity status
- ◆ Variable values can affect model execution
- ◆ Variable values are data to be collected

Similar to a cell in a spreadsheet  
or an algebraic expression

$$y = mx + b$$

	A	B	C	D
1				
2	Table			
3			Path1	
4				
5	Target			Speed
6				
7				

- ◆ Real
- ◆ Integer
- ◆ Arrays
  - Integer or real
  - 1, 2, or 3 dimensions
  - Indexed by a variable during a simulation
  - Think of them as tables with as many columns as you need



## ◆ tag

- A system variable that keeps track of the number of the entity being acted on by any event at any time
- Once you assign a value, it gets carried through
- In IMPRINT, tag denotes the operator number

## ◆ clock

- The current simulation time
- Starts at zero
- No expected resemblance to “real time”

## ◆ run

- When you have multiple runs of the network, this tells you which run you’re in
- Can be used to change conditions across runs

# *Naming Variables*

- ◆ We recommend that variable names start in Caps
- ◆ System variables are usually lower case
- ◆ Variables are global and if you change a system variable unintentionally, it will impact the model run
- ◆ Exception is counters

**SpeedRec[n]**

**Target**

**n**

**clock**

- ◆ Expressions are used to initially set or change variable values in Micro Saint & WinCrew models
  - Examples
    - » To set and change resource availability
    - » To set and change entity states
- ◆ Two general types - mathematical and logical expressions

# *Mathematical Expressions*

## ◆ Operators

( ) grouped operations

^ exponentiation

\* multiplication

/ division

% remainder division

+ addition

- subtraction

**clock/60**

**Speed/LapDist**

**Laps\*LapDist**

**n + 1**

## ◆ Logical operators

> greater than  
< less than  
>= greater than or equal to  
<= less than or equal to  
<> not equal to  
| logical or  
& logical and  
== equal to (e.g., if a== b then... )  
:= assignment

## ◆ Logical statements

if

then

else

if  $a > b$  then  $\text{Time} := 5$  else  $\text{Time} := 7$ ;

while ... do

while  $i < 5$  do  $\text{Type}[i] := 1, i = i + 1$ ;

## ◆ Adjustment operators

**$+=$**  Increment by adding

**$-$**  Increment by subtracting

**$/$**  Increment by dividing

**$*$**  Increment by multiplying

**$n+=1$**

**$m-=1$**

**$n=n+1$**

**$m=m-1$**



## ◆ Separators

- ; end of expression  
e.g., `a:=1;`
- , separates assignments within expressions  
e.g., `if a<1 then b:=5 , c :=6 else b:=4 ,  
c:=2;`

Comments are placed in curly brackets.

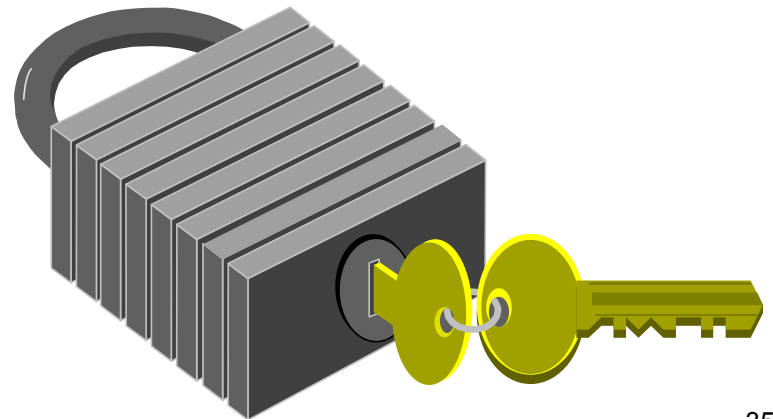
Note: All code must end in a ;

```
{This is an example of comments}1;
```

```
{When this task ends increment the task  
counter by 1} Taskcount+=1;
```

# *Release Conditions*

- ◆ Allows task to execute
- ◆ Establishes rules for task execution
- ◆ Condition must be true - 1=true, 0=false
- ◆ Can include multiple conditions
- ◆ Typically involves logical expressions



## ◆ Beginning effects

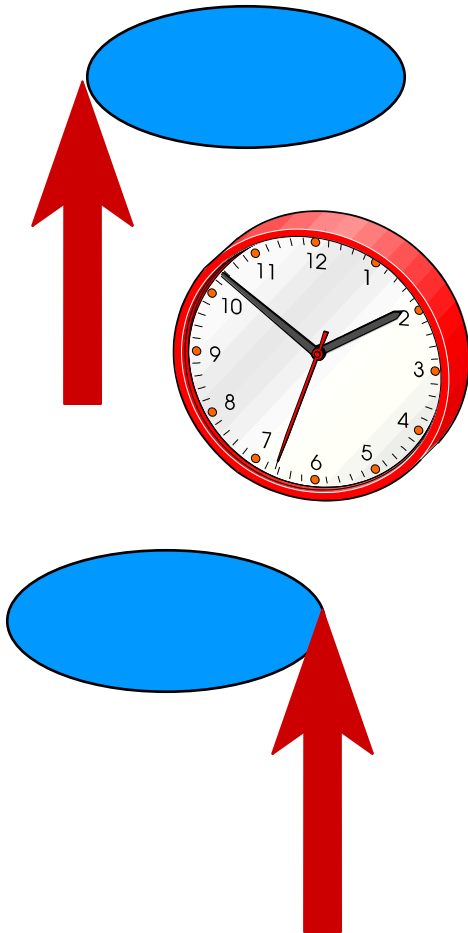
- What model conditions change as a result of a task beginning to execute

- ◆ e.g., resources are used, counters are incremented

## ◆ Ending effects

- What model conditions change as a result of a task completing execution

- ◆ e.g., resources are free, counters are decremented



- ◆ MicroSaint executes events in this order
  - Release conditions
  - Mean time
  - Beginning Effects
  - Ending Effects
    - Succeeding task(s)

- ◆ Expressions that are inserted into model execution at selected clock times
- ◆ Can be used to cause task execution
- ◆ Used commonly to
  - Establish initial conditions of the system
  - Insert system changes (e.g., arrival rates)

# *“Start” and “Stop” Logic*

# *Develop Your Own Analysis*



# Develop Your Own Analysis

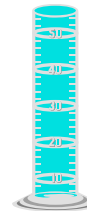
◆ Pick a Topic



◆ Develop a Question and Hypothesis



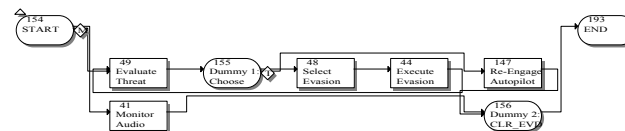
◆ Determine Measures



◆ Identify Functions and Tasks



◆ Build your Model



# *Does Your Model Run?*



**Yeah!!**



**So What???**



# *Your Model Runs – So What?*

- ◆ **Did it do what you wanted it to?**
  - First step is verification and debugging
- ◆ **How are you going to evaluate the results?**
  - Complete the analysis step
- ◆ **Is this realistic?**
  - Validate the model

## Verification, Validation, and Accreditation vs. Verification, Analysis, Validation, and Accreditation

- **Verification** means determining that the model does what it was meant to do
- **Analysis** of results means evaluating the results
- **Validation** means the model adequately represents the system
- **Accreditation** means that the model has been accredited for the use case

# *Debugging Tools*

- Step 1. Run model in IMPRINT
- Step 2. Open the IMPRINT directory
- Step 3. Open the correct version of MicroSaint
  - VACP model – vacpsaint.exe
  - Advanced model – crewsaint.exe
  - Goal model – goalsaint.exe
- Step 4. Open the model
  - VACP model – imprint.mod
  - Advanced model – saint.mod
  - Goal model – cart.mod
- Step 5. Run the model – Single step using Ctrl t

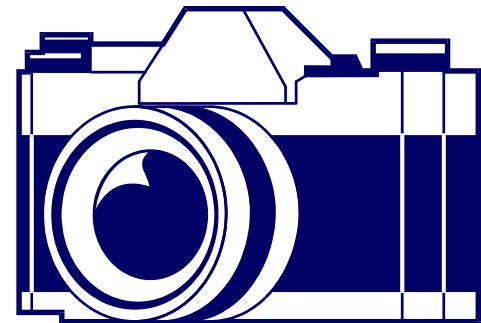
Note: No changes will be saved. You must go back and make the changes in IMPRINT.

# Event Queue

cart.mod : Event Queue					
Time	Tag	Group	Type	Event	
1.89587	1	0	→	10001 Cmdr Driver	
1.89587	0	0	≡	215 QUEUE FOR: Continue	
1.89587	9990	0	→	9990 goalstat1	
1.89587	9999	0	→	9999 trigger parser	
1.89587	0	0	≡	206 QUEUE FOR: Decide Path & Speed CD	
1.89743	0	0	→	205 Recognize Path CD	
1.90091	0	0	→	217 Assess Vehicle Function CD	
1.90297	0	0	→	214 Assess Vehicle Motion CD	
1.91778	0	0	→	212 Assess Vehicle Orientation CD	
1.92436	0	0	→	199 Don't Steer	
2.03703	0	0	→	198 Coast CD	
6.08793	155	0	→	156 Send voice message CD	
10.08793	168	0	→	170 monitor + update IVIS (random 1-10s) Gunner	
11.60162	81	0	→	89 CD inputs report via IVIS	
23.31807	176	0	→	187 crew comm2 continues delay random	

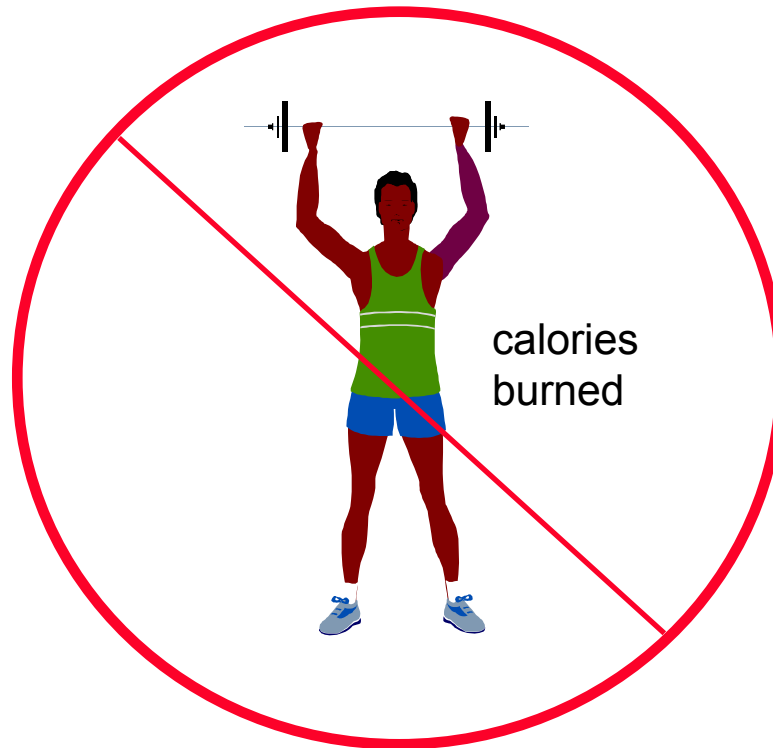
# *Snapshots of Execution*

- ◆ Used to collect data during a model run
- ◆ Each snapshot defines variables to be stored during execution
- ◆ Data collection can be triggered on
  - Task execution
  - Entities going into or departing from queues
  - Clock time
  - End of the run





*What is mental workload?*



# *What Is Mental Workload?*

## An Example

- ◆ Drivers slowing down to talk on their cell phone
- ◆ Accident rates of drivers using cell phones approaches that of drivers under the influence of alcohol





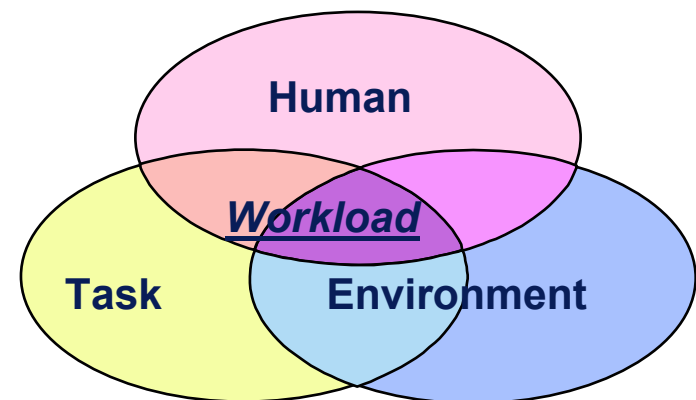
# *Why You Should Care About Workload*

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- ◆ If you reduce crewsize then some tasks must be automated or redistributed among remaining crew positions
  - Reallocation of tasks is likely to increase workload, thus increasing the potential for performance failures and errors.
  - Poorly designed automation can also increase workload and thus the potential for human errors.

## ◆ Workload Definition

- There is no universally agreed-upon definition
- Today, however, there is generally agreement that, essentially, workload is
  - » *the perceived relationship between the amount of mental processing capacity or resources and the amount required by the task*



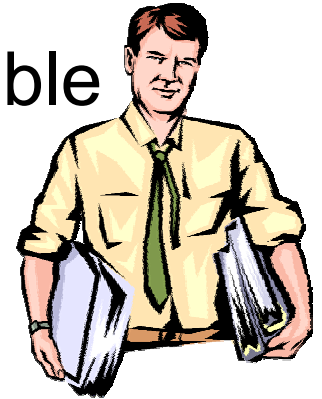


# *Mental Workload Issues*

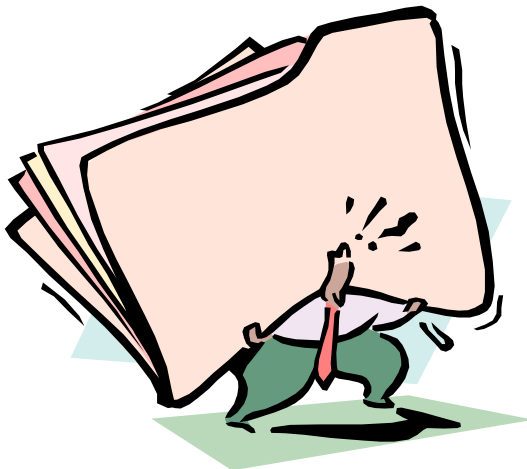
- ◆ Sustained low workload (underload) leads to boredom, loss of situation awareness, and reduced alertness.
- ◆ Sustained high workload (overload) leads to fatigue.
- ◆ Workload peaks lead to dropped tasks, increased task time, cognitive tunneling, and increased errors.
- ◆ These factors reduce crew performance, system performance, and contribute to mission failure

# *Mental Workload Objective*

Achieve evenly distributed, manageable workload.



Avoid both overload and underload.





# *Various Mental Workload Measurement Approaches*

## **empirical**

- ◆ physiological
- ◆ primary task
- ◆ secondary task
- ◆ subjective rankings

## **analytical**

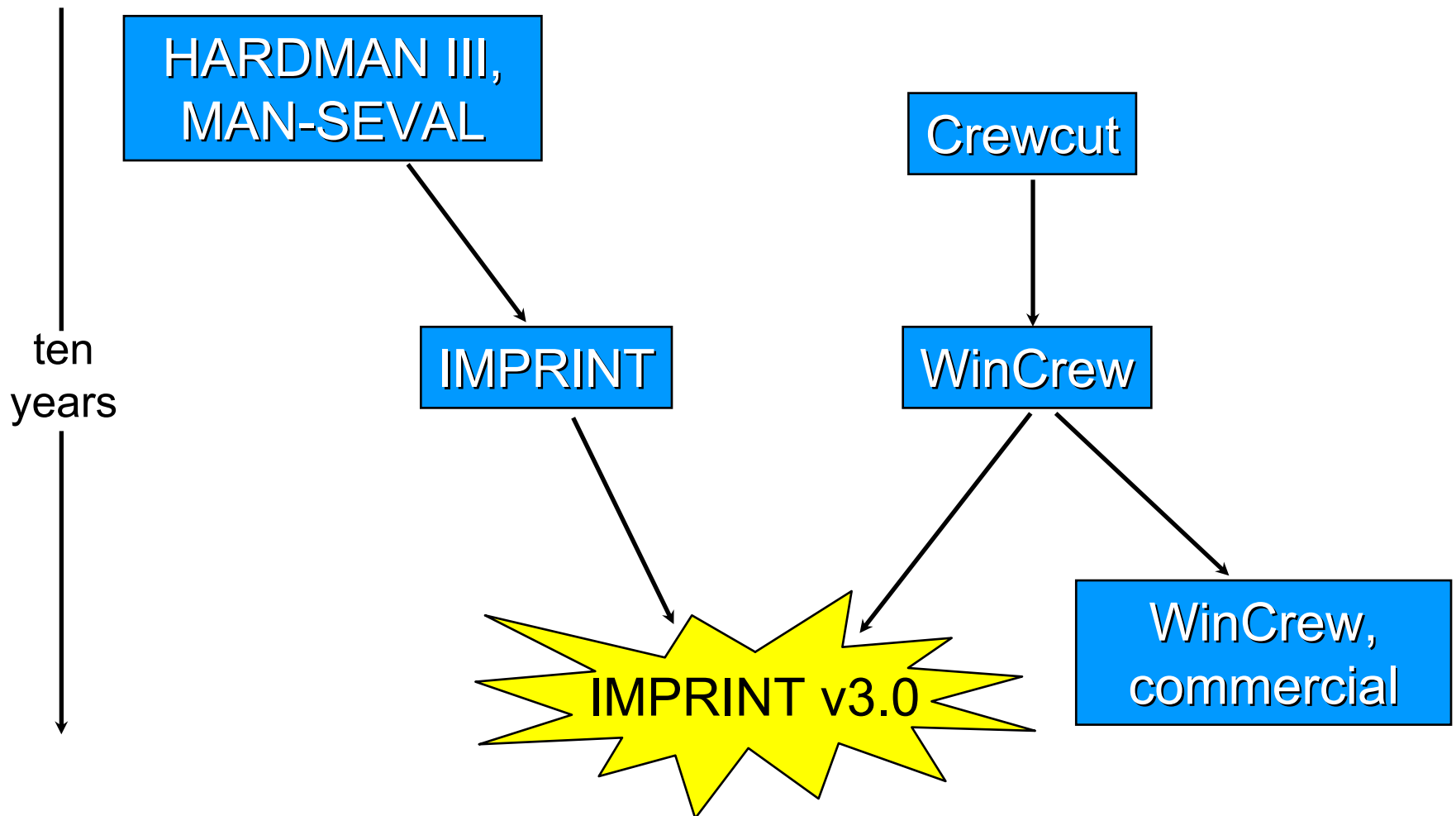
- ◆ workload modeling-  
IMPRINT



- ◆ Workload modeling of human behavior is a technique that has been used to *predict* workload levels. Many different models have been proposed to model human behavior and measure workload.

- ◆ Workload modeling of human behavior is a technique that has been used to *predict* workload levels.
  - IMPRINT can be used to model and predict mental workload.

# ARL HRED Workload Modeling Tools





# *IMPRINT Workload Modeling*

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- ◆ workload predictions are used to estimate operator performance and its effect on system performance

*What is advanced IMPRINT workload?*

# Multiple Resources Theory of Mental Workload

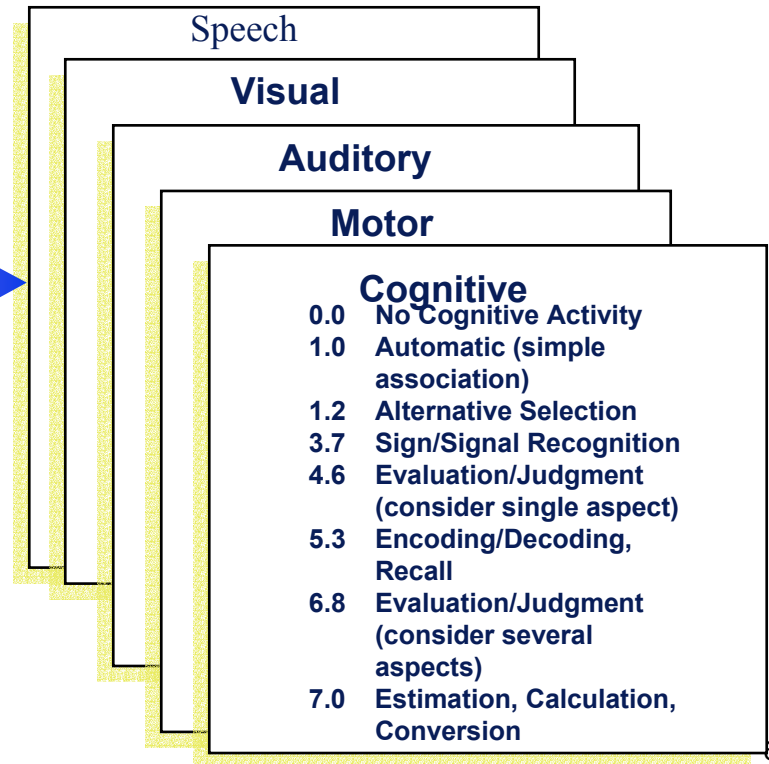
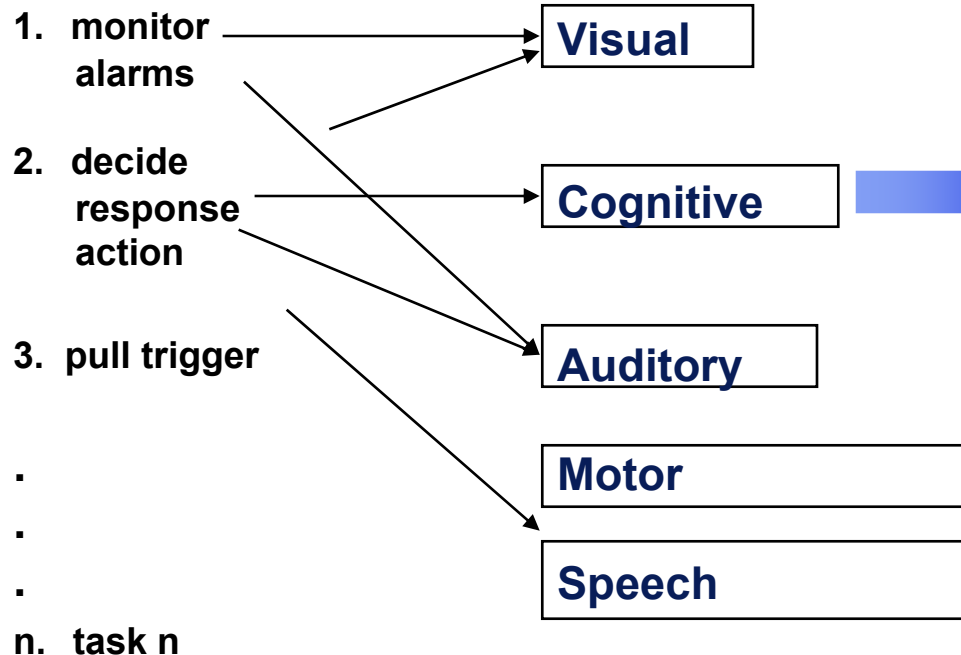
**Mission  
Tasks**



**Which Brain  
Resources  
Involved?**



**Degree of  
Resource Use?**



## ADVANCED WORKLOAD CALCULATION:

$$W_T = W_{STD} + (W_{WCC} + W_{BCC})$$

**Where:**

$W_T$  = Instantaneous Workload at Time T

$W_{STD}$  = Workload attributable to the demands of all operator's tasks at time T (Single Task Demands)

$W_{WCC}$  = Workload attributable to Within-Channel Conflicts (Within and between tasks)

$W_{BCC}$  = Workload attributable to Between-Channel Conflicts (Between tasks only; within tasks may see improved performance "S-C-R")

# *Workload & Crewstation Parameters*



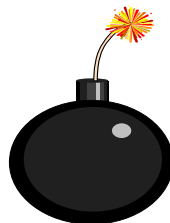
# *Define Resources and Interfaces*

## **Resources**

- ◆ Default set
  - Visual
  - Auditory
  - Motor
  - Speech
  - Cognitive
- ◆ Add up to 5 more

## **Interfaces**

- ◆ Controls and displays in your design
- ◆ Don't get carried away!



**Be prudent!**

# *Assign Single Task Demands*

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- ◆ Pair resources with interfaces
- ◆ Assign resource interface pairs to tasks
- ◆ Estimate single task demands for tasks

Pop-up scales accessed by double-clicking the cell

# *Assign Conflicts*

- ◆ BIG contributor to workload score
- ◆ Penalties for using resource interface pairs
- ◆ Cell values range from 0.00 -1.00
- ◆ Double click on row header provides “expert guidance” and default values



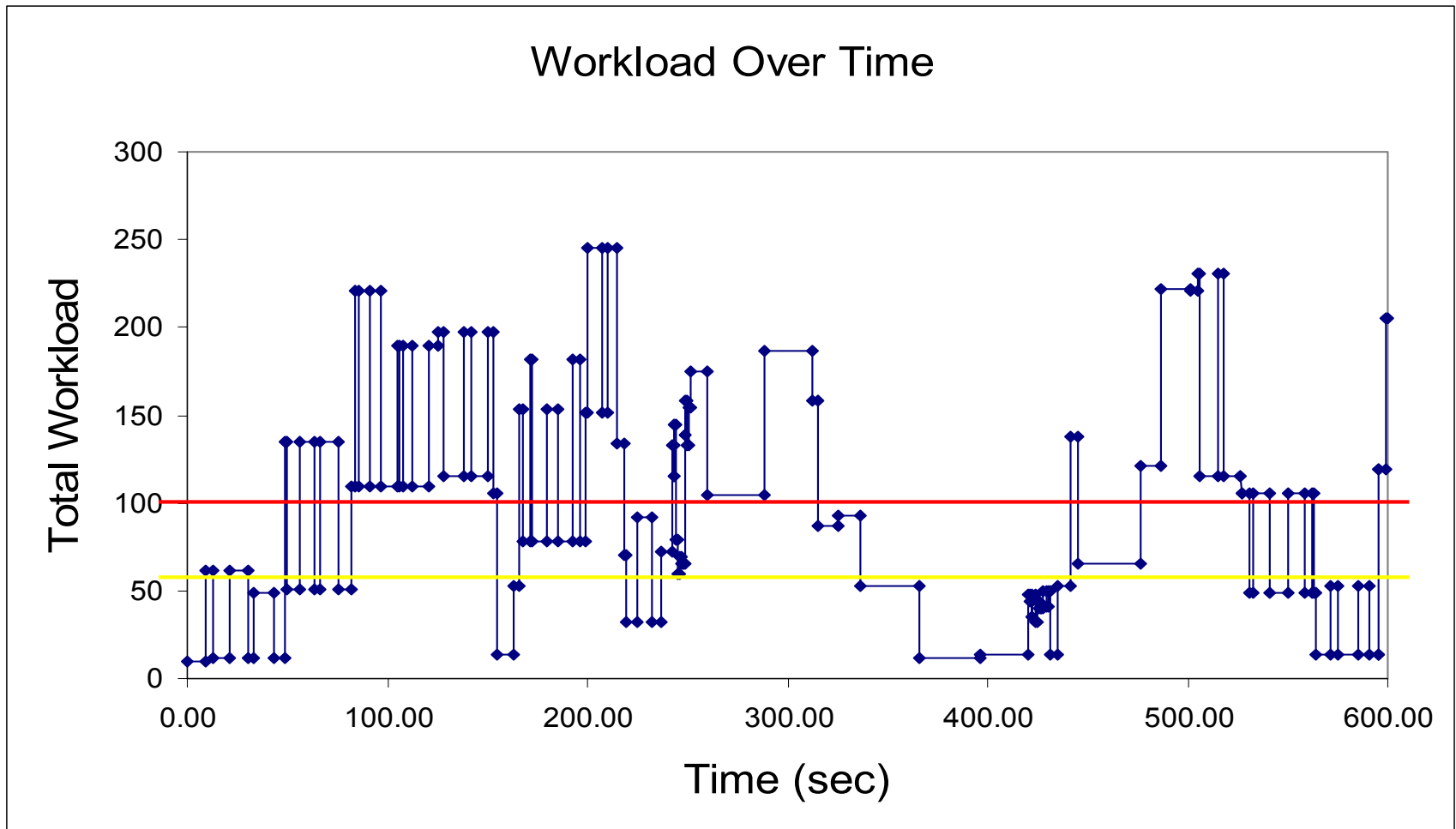
# *Advanced Workload Method*

- ◆ Describes effort needed to perform task
- ◆ To help examine impact of workload during mission
- ◆ Results are combined across channels into one score
- ◆ Results consider inter- & intra-channel conflict
- ◆ Does dynamically impact performance

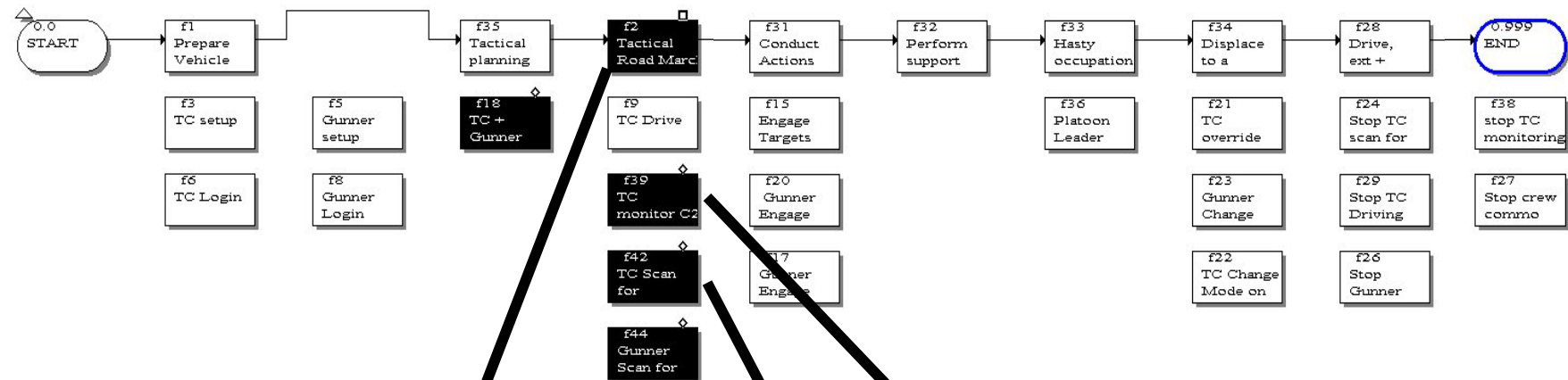
**Time, Accuracy, Crew Allocation, Sequence**

# *Workload Threshold*

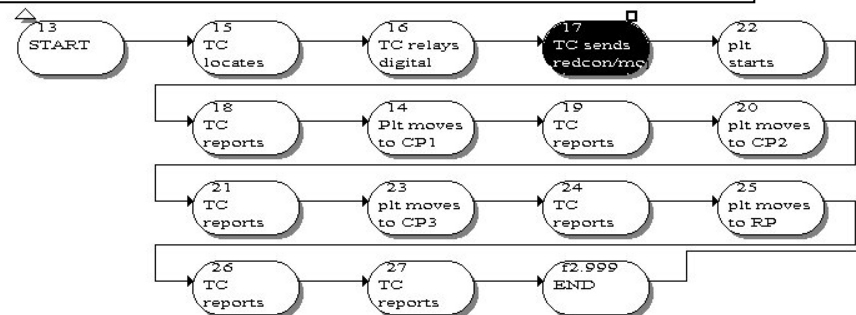
# *FCS Modeling Results CG*



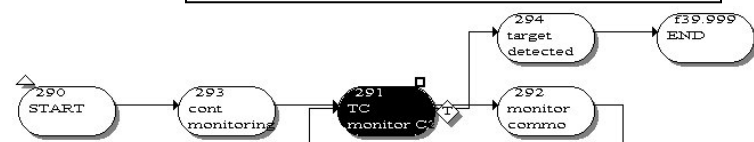
# Scenario 1 - Tank Mission at run time 2411.2



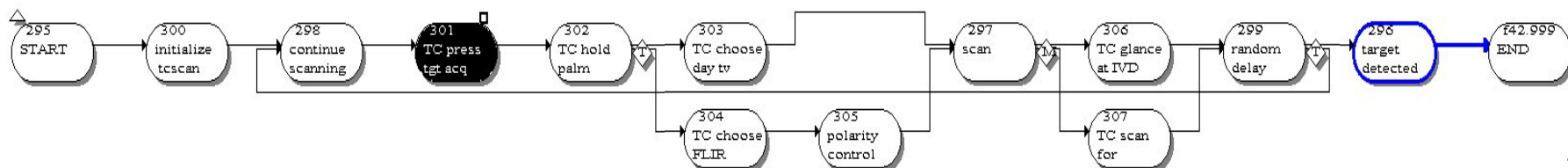
## Movement to contact - function



## Monitor C2 - function



## TC Target Scan - function



# *Analysis of Results*



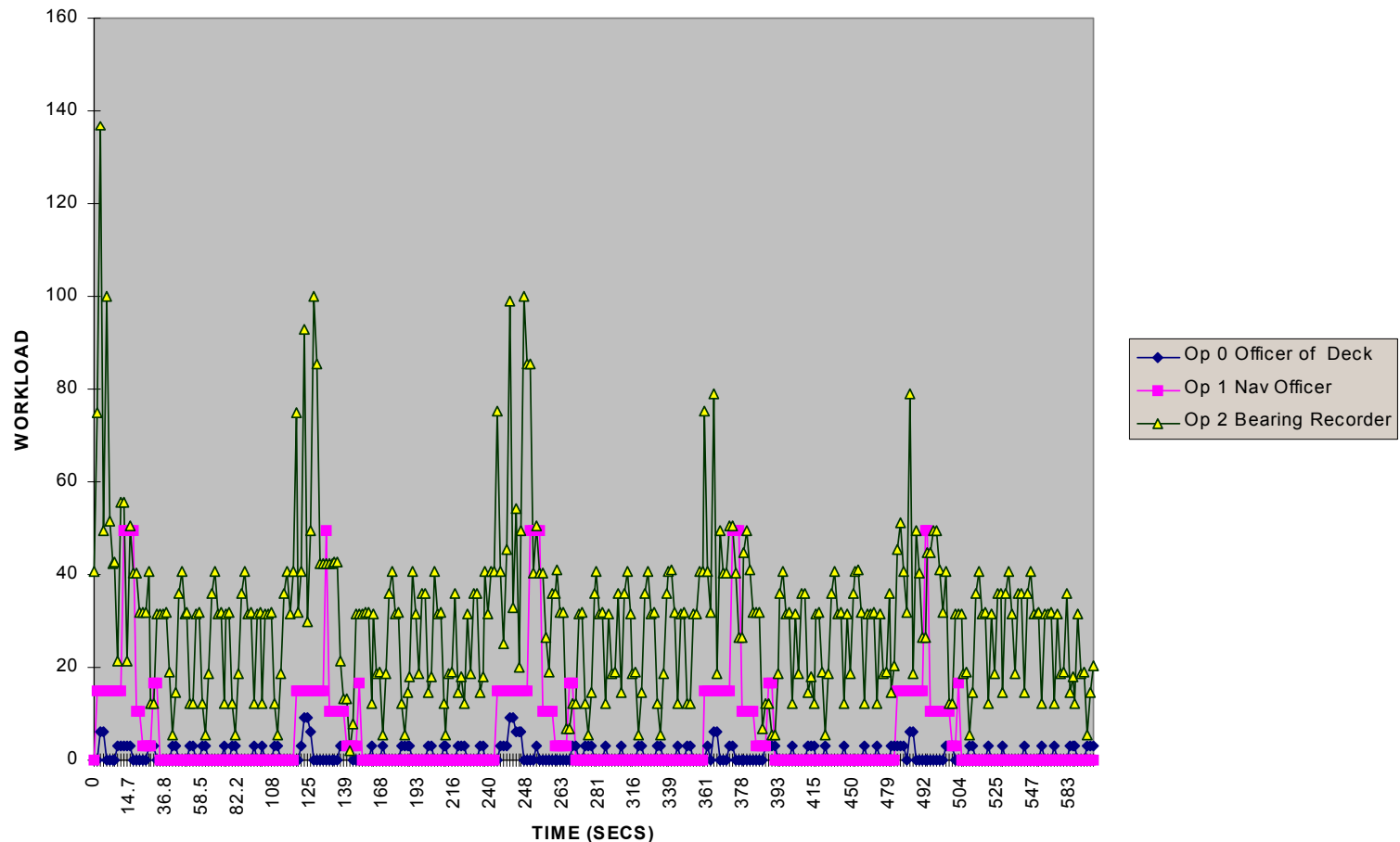
# *Unique Outputs of Advanced Workload*

- ◆ Critical Path
- ◆ Operator Activity
- ◆ Operator Workload
- ◆ Overload
- ◆ Channel Conflict
- ◆ Task Timeline
- ◆ CrewStation Workload
- ◆ User Snapshot



# Sample WinCrew Output

**REDUCED, POOR AUTOMATION, GOOD ALLOCATION**



# *Displaying your results*

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- ◆ Consider your audience
- ◆ Display your results accordingly
  - Spreadsheets
  - Tables
  - Graphs

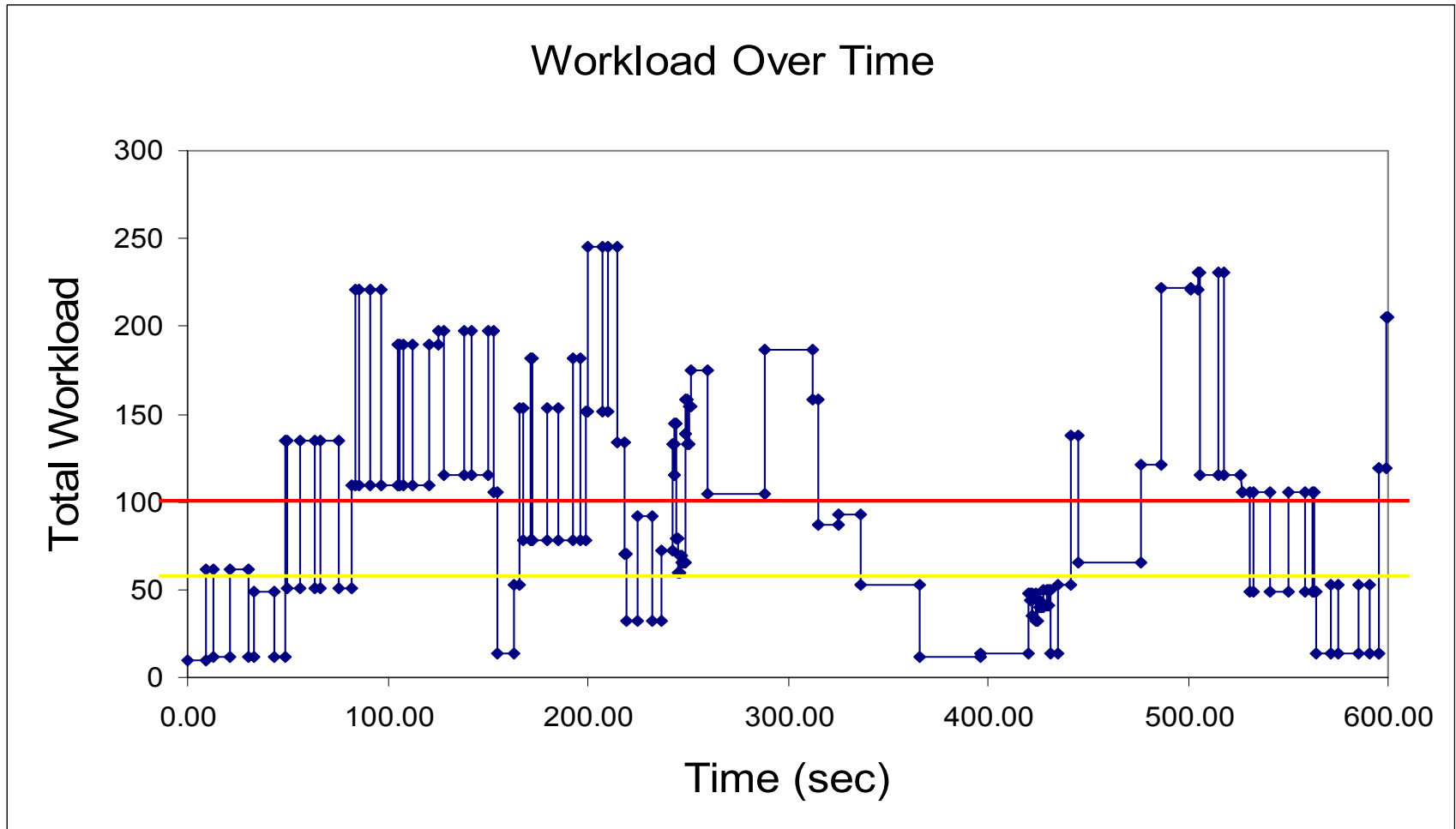
# Results - spreadsheets

Thresholds		Results							
T1 =	60	Number of Times over 60				Number of Times over 100			
T2 =	100	Percent of time in 60				Percent of time in overload 100			
		Max Workload Value				Min Workload Value			
		97				59			
		39.8%				24.0%			
		283.9				7			
Time	Workload	T1				T2			
		>?	Secs >			>?	Secs>		
0	14.7	0	0			0	0		
3	58.01	0	0			0	0		
8	13.5	0	0			0	0		
9	54.6	0	0			0	0		
12	32.11	0	0			0	0		
14	38.67	0	0			0	0		
15.89	42.09	0	0			0	0		
16	106.91	1	2			1	2		
18	244.18	1	1			1	1		
19	155.93	1	2			1	2		
21	7	0	0			0	0		
23	29.66	0	0			0	0		
25	48.96	0	0			0	0		
25.12	99.93	1	3.88			0	0		
29	13.2	0	0			0	0		
31	14.7	0	0			0	0		
31.06	57.86	0	0			0	0		
34	76.89	1	0.69			0	0		
34.69	163.74	1	2.31			1	2.31		
37	69.99	1	2			0	0		

# Results - tables

	<b>Combat</b>	<b>AutoScan</b>	<b>Baseline</b>	<b>Non-Combat</b>
	T1 = 60	T1 = 60	T1 = 60	T1 = 60
Number of Times over T 1	112	91	97	50
Percent of time in overload > T 1	46.9%	37.7%	39.8%	34.2%
Max Workload Value	244.18	287.02	283.9	245.82
Min Workload Value	7	3	7	7
<hr/>				
	T2 = 100	T2 = 100	T2 = 100	T2 = 100
Number of Times over T 2	69	44	59	29
Percent of time in overload > T 2	28.3%	19.1%	24.0%	23.5%

# Results - graphs



# *Goal Oriented Modeling*

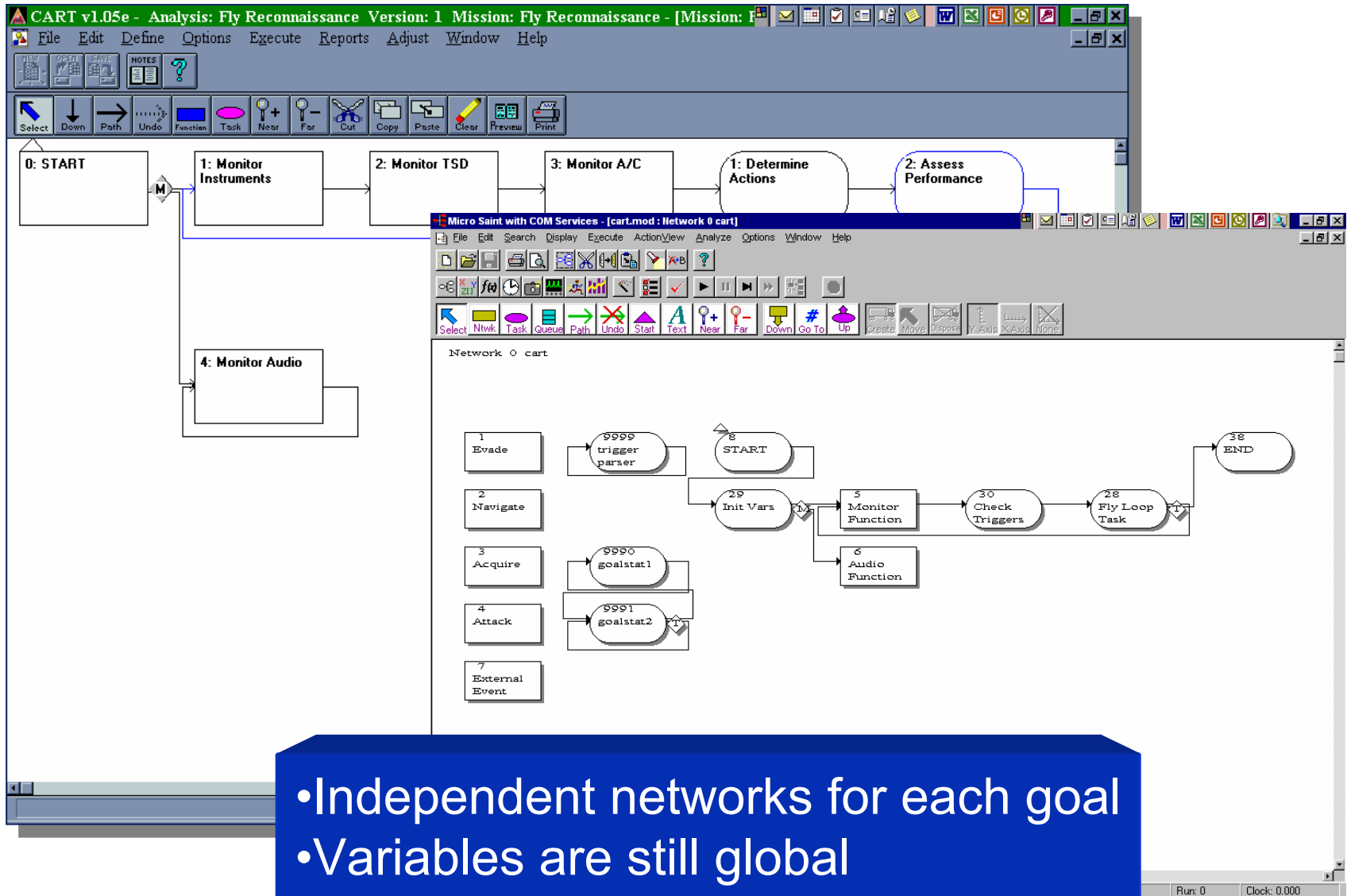


# *Goal Oriented Modeling*

- ◆ Goal orientation
  - Option from VACP
  - Beginning & Ending Effects
  - Variable Catalog
  - Macros (User-Defined Functions)
  - Snapshots
- ◆ COM capabilities
  - Including HLA Middleware
- ◆ Access to tag

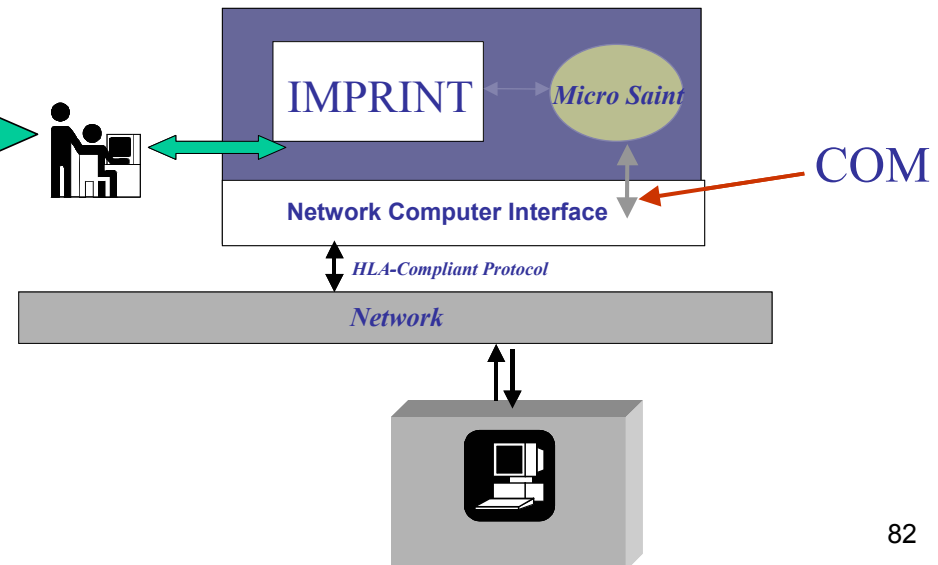
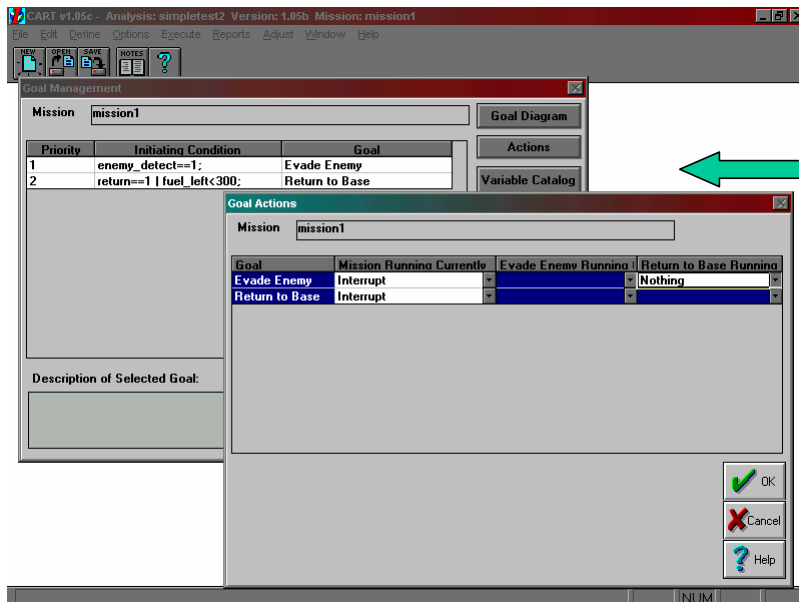


# Task Network Model Development

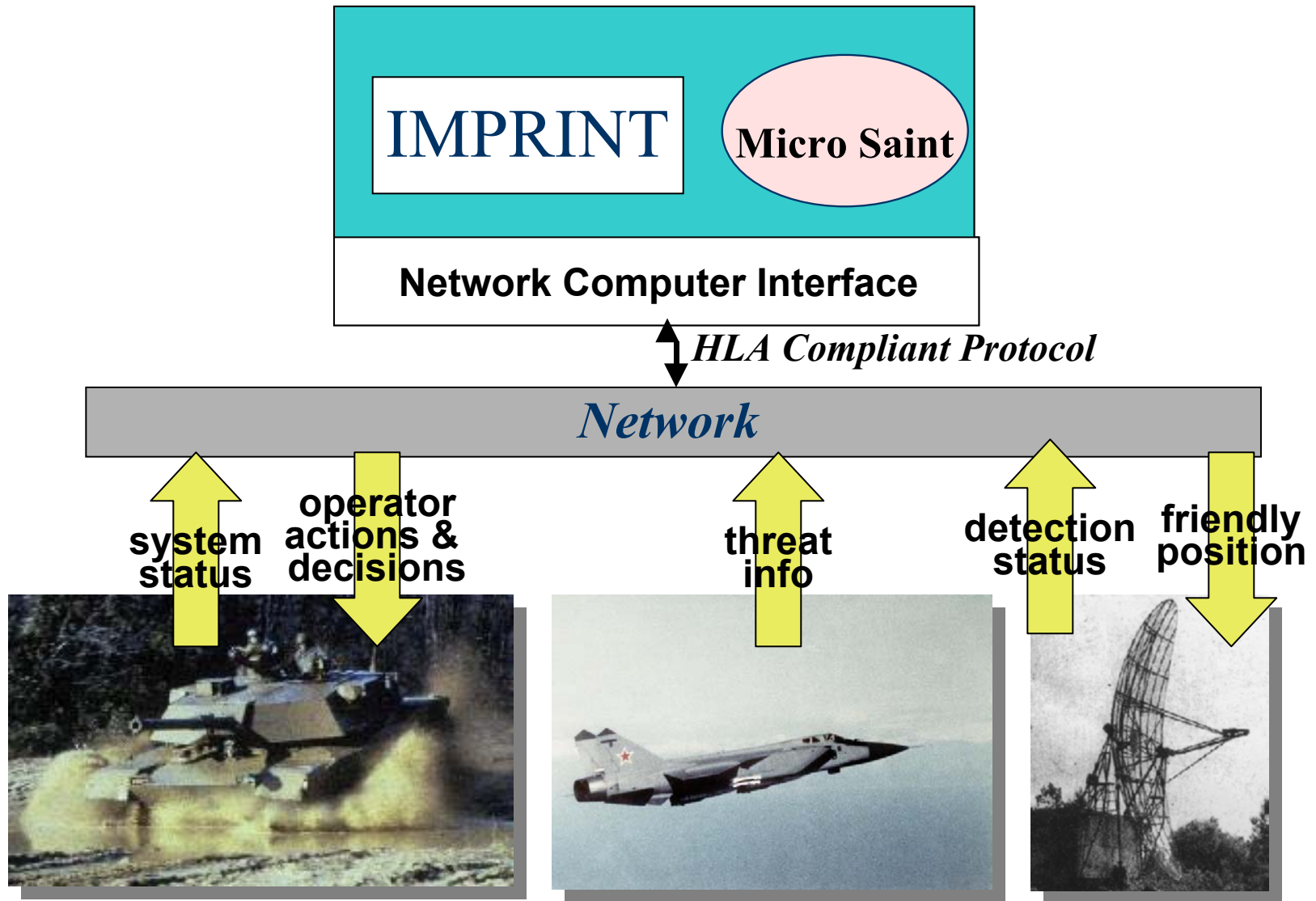


- Independent networks for each goal
- Variables are still global

- ◆ Trigger identification
- ◆ Trigger communication
- ◆ Task interruption
- ◆ Task restart vs. task resume



# System Architecture





- ◆ AF Validation Success Story
  - Wright Pat SIMAF Virtual Strike Warfare Environment
  - Time critical targeting (SCUD Hunt) mission
  - HPM vs. Eight pilots (F16 and A10)
  - Overall kills of ground targets in the time critical scenario was virtually the same for both the model and pilots (100% and 98%, respectively)
  - HPM accounted for 61 percent of the behavior of the pilots in the simulation environment
  - New tactic discovered: Coordinated use of synthetic aperture radar (SAR) and targeting infrared (TIR) imaging system



# *Why would you use Goal-Oriented?*

---

- 1. When you want VACP workload and the ability to use effect modeling**
- 2. When you want to represent human behavior using goals**
- 3. When you need to talk to other simulations**

You can switch from VACP or Advanced to Goal oriented with caveats!

---

# *Review Advanced Modeling Capabilities*



# *Advanced Modeling Details*

---

- ◆ Variables
- ◆ Mathematical and Logical Expressions
- ◆ Beginning Effects
- ◆ Ending Effects
- ◆ Release Conditions
- ◆ Data Collection

Comments are placed in curly brackets.

Note: All code must end in a ;

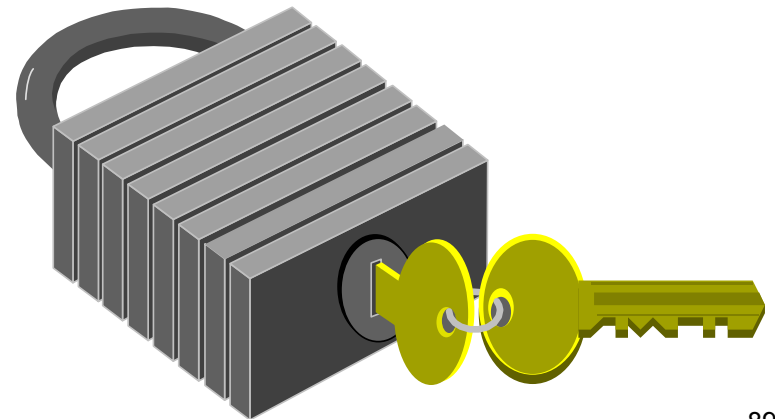
```
{This is an example of comments}1;
```

```
{When this task ends increment the task  
counter by 1} Taskcount+=1;
```



# *Release Conditions*

- ◆ Allows task to execute
- ◆ Establishes rules for task execution
- ◆ Condition must be true - 1=true, 0=false
- ◆ Can include multiple conditions
- ◆ Typically involves logical expressions



## ◆ Beginning effects

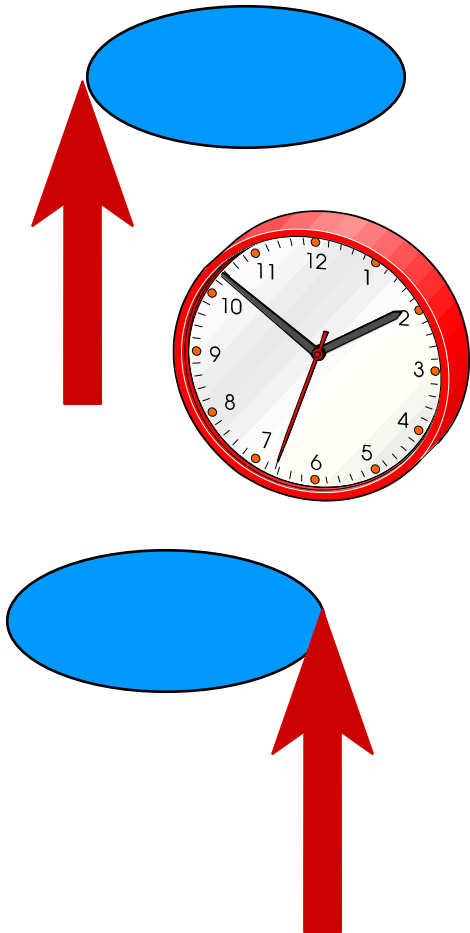
- What model conditions change as a result of a task beginning to execute

- ◆ e.g., resources are used, counters are incremented

## ◆ Ending effects

- What model conditions change as a result of a task completing execution

- ◆ e.g., resources are free, counters are decremented





# *Order of Events*

- ◆ MicroSaint executes events in this order
  - Release conditions
  - Mean time
  - Beginning Effects
  - Ending Effects
    - Succeeding task(s)

- ◆ Expressions that are inserted into model execution at selected clock times
- ◆ Can be used to cause task execution
- ◆ Used commonly to
  - Establish initial conditions of the system
  - Insert system changes (e.g., arrival rates)



# Debugging Hints

- Step 1. Run model in IMPRINT
- Step 2. Open the IMPRINT directory
- Step 3. Open the correct version of MicroSaint
  - VACP model – vacpsaint.exe
  - Advanced model – crewsaint.exe
  - Goal model – goalsaint.exe
- Step 4. Open the model
  - VACP model – imprint.mod
  - Advanced model – saint.mod
  - Goal model – cart.mod
- Step 5. Run the model – Single step using Ctrl t

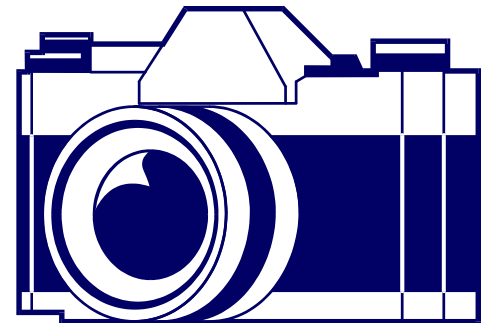
Note: No changes will be saved. You must go back and make the changes in IMPRINT.

# Event Queue

cart.mod : Event Queue				
Time	Tag	Group	Type	Event
1.89587	1	0	→	10001 Cmdr Driver
1.89587	0	0	≡	215 QUEUE FOR: Continue
1.89587	9990	0	→	9990 goalstat1
1.89587	9999	0	→	9999 trigger parser
1.89587	0	0	≡	206 QUEUE FOR: Decide Path & Speed CD
1.89743	0	0	→	205 Recognize Path CD
1.90091	0	0	→	217 Assess Vehicle Function CD
1.90297	0	0	→	214 Assess Vehicle Motion CD
1.91778	0	0	→	212 Assess Vehicle Orientation CD
1.92436	0	0	→	199 Don't Steer
2.03703	0	0	→	198 Coast CD
6.08793	155	0	→	156 Send voice message CD
10.08793	168	0	→	170 monitor + update IVIS (random 1-10s) Gunner
11.60162	81	0	→	89 CD inputs report via IVIS
23.31807	176	0	→	187 crew comm2 continues delay random

# *Snapshots of Execution*

- ◆ Used to collect data during a model run
- ◆ Each snapshot defines variables to be stored during execution
- ◆ Data collection can be triggered on
  - Task execution
  - Entities going into or departing from queues
  - Clock time
  - End of the run



# *Goal Matrix*



## Goal Management

Mission:

Priorit	Initiating Condition	Goal
1	threat_present==TRUE & mission_time_left < 14.5;	Evade
2	target_present==TRUE & evade_status == FALSE;	Attack

Triggering conditions  
(from internal and  
external simulations)

Description of Selected Goal:

Goal Diagram

Actions

Variable Catalog

Add Goal

Cut Goal

OK

Cancel

Help

## Goal Actions

Mission

Goal	Mission Running Curr	Evade Running Curr	Attack Running Curr
Evade	<input type="text" value="Interrupt"/>	<input type="text" value=""/>	<input type="text" value="Abort"/>
Attack	<input type="text" value="Interrupt"/>	<input type="text" value=""/>	<input type="text" value=""/>

Action matrix – to define  
goal interactions



## ◆ When a trigger comes true:

- Look UP the matrix to see if a higher priority goal would suspend or halt it. If so, don't start it, but keep trying.

If not:

- Look DOWN the matrix and implement the actions for all lower priority goals

## ◆ When a goal ends normally, gets halted or gets suspended:

- Resume anything it suspended UNLESS a higher priority goal would halt it. If so, halt it. If a higher priority goal would suspend it, then suspend it.



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# *Review of IMPRINT Capabilities*

# Using IMPRINT

IMPRINT MODULES		DEFINE MISSION			DEFINE EQUIPMENT	DEFINE SOLDIER	DEFINE SUPPLY
		VACP Modeling	Advanced Modeling	Goal Oriented			
CAPABILITIES	Interface Technique						
	Data Entry				✓	✓	✓
	Graphical Toolbar	✓	✓	✓			
	Embedding Coding		✓	✓			
	Additional Capabilities						
	VACP Workload	✓		✓			
	Advanced Workload		✓				
	PTS	✓		✓	✓		

*Wrap up and  
Discussion!*

- ➡ Save ! Save! Save!
- ➡ Never too many DUMMIES...
- ➡ Naming Conventions



# *Getting the Software*

## **Who**

- ◆ Any government agency
- ◆ Private industry with government contract
- ◆ Foreign government (case-by-case)

## **How**

- ◆ Send request via e-mail or letter
- ◆ If private industry include government contract number and organization

## **Non-Distribution Form**

- ◆ Keep track of users
- ◆ Reminder not to distribute

## **Software Distribution**

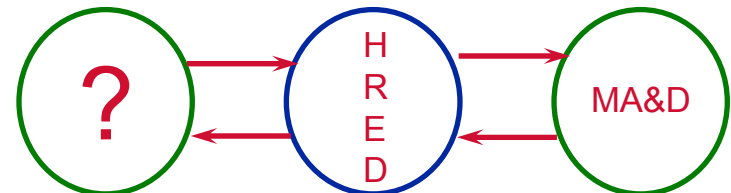


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(410) 278-8830
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(410) 278-5877

## Maintain Database

- ◆ User comments
- ◆ “Bugs”
- ◆ “Fixes”





# *Using the List Server*

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List of current IMPRINT users & interested parties

Send suggestions, comments, general information or questions regarding IMPRINT to

[imprint@arl.army.mil](mailto:imprint@arl.army.mil)



# References

- ◆ Allender, L., Kelley, T. D., Salvi, L., Lockett, J., Headley, D. B., Promisel, D., Mitchell, D., Richer, C., and Feng, T. Verification, validation, and accreditation of a soldier-system modeling tool. Proceedings of the Human Factors and Ergonomics Society 39th Annual Meeting-1995, San Diego, pp. 1219-1223.
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- ◆ Allender, L., Kelley, T., Archer, S., and Adkins, R., (1997). IMPRINT The Transition and Further Development of a Soldier-System Analysis Tool. MANPRINT Quarterly, Office of the Deputy Chief of Staff of Personnel, Vol. V, No. 1.
- ◆ Dahl, S., Allender, L., and Kelley, T., (1995) Transitioning Software to the Window Environment - Challenges and Innovations. Proceedings of the Human Factors and Ergonomics Society 39th Annual Meeting - 1995, San Diego, pp. 1224-1227.
- ◆ McMahon, R., Spencer, M., and Thornton, A. (1995). A quick response approach to assessing the operation performance of the XM93E1 NBCRS through the use of modeling and validation testing. Presented at the Military Operations Research Society Symposium.
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- ◆ Mitchell, D. K. (2000). Mental workload and ARL workload modeling tools. (ARL-TN-161) Aberdeen Proving Ground, MD: Army Research Laboratory.
- ◆ Mitchell, D., Samms, C., Henthorn, T., Wojciechowski, J. (2003). Trade Study: A Two-Versus Three-Soldier Crew for the Mounted Combat System (MCS) and Other Future Combat System Platforms. (ARL-TR-3026) Aberdeen Proving Ground, MD: Army Research Laboratory.